SPECIALIZED INERTIAL NAVIGATION SOLUTION FOR HIGH SHOCK ARTILLERY ENVIRONMENTS
Possibilities of Navigation. Made Easy
aTALIN™

Ultra-rugged, reliable, best-value INS/GPS navigator with embedded GPS receiver

System Features
- Honeywell’s next generation ring laser gyro technology combined with our best in class accelerometers and protected by an enhanced internal isolation system for unparalleled performance in the most demanding military and commercial environments, including mounted directly on artillery platforms.
- Does not require external: isolation, GPS receiver, or GPS antenna.
- Single system plug "N" play across multiple platforms - auto-configuration adaptable.
- Align while stationary or on the move.
- Multiple accuracy configurations to meet different applications requirements.
- Over 15,000 systems from the TALIN family fielded on over 60 military and commercial platforms worldwide including combat vehicles, sensor platforms, towed and self-propelled weapons, survey applications, and mining equipment.

System Characteristics

Operating Ranges
- Attitude: Alignment and orientation in any direction, and on the move
- Angular rate: ±200 deg/sec

Reliability
- MTBF: >50,000 hours (TALIN demonstrated)

Power Requirements
- 23–33 Vdc: <40 watts*

Thermal Operating Range
- No cooling required: -46°C to 71°C (-51°F to 160°F)

Navigation Sensors
- Standard/Internal: 3-axis inertial sensors and PPS MPE-S or SPS Polaris Link GPS Receiver
- Optional/External: VMS

Software
- Modular – partitioned for cost-effective system missionization.
- Field upgradeable

Weight
- <24 pounds (11kg)

Interfaces
- Standard: 10/100 Ethernet
- Optional: RS-422/RS-232

Form Factor - (excluding flanges & connectors)
- Approx. 6.8 H x 9.5 W x 12.0 L inches
- Approx. 17 H x 24 W x 30 L cm

Installation
- Can be hard mounted in any orientation (Shock tolerance maximized when connectors are forward or aft).

*Application and configuration dependent

<table>
<thead>
<tr>
<th>PERFORMANCE</th>
<th>ATALIN 2000</th>
<th>ATALIN 3000</th>
<th>ATALIN 4000</th>
<th>ATALIN 5000</th>
<th>ATALIN 6000</th>
</tr>
</thead>
<tbody>
<tr>
<td>HORIZONTAL POS</td>
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<tr>
<td>INU only</td>
<td>35m</td>
<td>25m</td>
<td>18m</td>
<td>12m</td>
<td>6m</td>
</tr>
<tr>
<td>INU/VMS</td>
<td>35m</td>
<td>25m</td>
<td>18m</td>
<td>12m</td>
<td>10m</td>
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<tr>
<td>INU/VMS/GPS PPS</td>
<td>&lt;10m CEP</td>
<td>&lt;10m CEP</td>
<td>&lt;10m CEP</td>
<td>&lt;10m CEP</td>
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<tr>
<td>INU/VMS/GPS SPS</td>
<td>&lt;60m CEP</td>
<td>&lt;60m CEP</td>
<td>&lt;60m CEP</td>
<td>&lt;60m CEP</td>
<td>&lt;60m CEP</td>
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<tr>
<td>HEADING/POINTING ACCURACY</td>
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<tr>
<td>Specified Accuracy (RMS) at ±65° Latitude</td>
<td>&lt;4.0 mils</td>
<td>&lt;2.0 mils</td>
<td>&lt;1.0 mils</td>
<td>&lt;0.70 mils</td>
<td>&lt;0.50 mils</td>
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<tr>
<td>sec(lat)</td>
<td>&lt;1.69 mils</td>
<td>&lt;0.85 mils</td>
<td>&lt;0.42 mils</td>
<td>&lt;0.3 mils</td>
<td>&lt;0.21 mils</td>
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<td>PITCH AND ROLL ACCURACY</td>
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<tr>
<td>(RMS)</td>
<td>&lt;1.00 mils</td>
<td>&lt;1.00 mils</td>
<td>&lt;0.50 mils</td>
<td>&lt;0.35 mils</td>
<td>&lt;0.25 mils</td>
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<td>MAX ALIGNMENT TIME</td>
<td></td>
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<td>Maximum Static Alignment Time</td>
<td>&lt;5.0 minutes</td>
<td>&lt;5.0 minutes</td>
<td>&lt;10.0 minutes</td>
<td>&lt;15.0 minutes</td>
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<tr>
<td>Maximum Dynamic Alignment Time</td>
<td>&lt;12.0 minutes</td>
<td>&lt;12.0 minutes</td>
<td>&lt;12.0 minutes</td>
<td>&lt;16.0 minutes</td>
<td>&lt;16.0 minutes</td>
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<tr>
<td>Typical Alignment Time (28° Latitude)</td>
<td>&lt;2.5 minutes</td>
<td>&lt;3.0 minutes</td>
<td>&lt;4.5 minutes</td>
<td>&lt;4.5 minutes</td>
<td>&lt;5.5 minutes</td>
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Values shown are per definitions in aTALIN system specifications

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