HIT YOUR TARGET IN ANY ENVIRONMENT
gTALIN

Flexible, reliable best-value INS/GPS navigator with embedded GPS receiver

SYSTEM FEATURES

• Honeywell’s next generation ring laser gyro technology combined our best in class accelerometers and coupled with an embedded GPS receiver for unparalleled performance in the most demanding military and commercial environments without the need for secondary shock isolation.

• Single system plug “N” play across multiple platforms - auto-configuration adaptable.

• Instant on! On-the-move alignment.

• Multiple accuracy configurations to meet different applications requirements.

• Over 15,000 TALIN systems fielded on over 60 military and commercial platforms worldwide including combat vehicles, sensor platforms, towed and self-propelled weapons, survey applications, and mining equipment.

SYSTEM CHARACTERISTICS

Operating Ranges

• Attitude: Alignment and orientation in any direction, and on the move

• Angular rate: ±200 deg/sec

Reliability

• MTBF: >50,000 hours (TALIN demonstrated)

Power Requirements

• 18-32 Vdc: <30 watts*

Thermal Operating Range

• No cooling required: -46°C to 71°C (-51°F to 160°F)

Navigation Sensors

• Standard/Internal: 3-axis inertial sensors and PPS MPE-S or SPS Polaris Link GPS Receiver

Optional/External: VMS

Software

• Modular – partitioned for cost-effective system missionization

• Field upgradeable

Weight

• <15 pounds (<7kg)

Interfaces

• Standard: 1553A&B/RS-422/RS-232 serial host interface

• Optional: Additional RS-422/RS-232 data interface, turret encoders, laser range finders

Form Factor - (excluding flanges & connectors)

• Approx. 5.4 H x 7.6 W x 10.3 L inches

• Approx. 14 H x 19 W x 26 L cm

Installation

• Can be hard mounted in any orientation

*Application and configuration dependent

PERFORMANCE

<table>
<thead>
<tr>
<th>HORIZONTAL POS</th>
<th>GTALIN 2000</th>
<th>GTALIN 3000</th>
<th>GTALIN 4000</th>
<th>GTALIN 5000</th>
<th>GTALIN 6000</th>
</tr>
</thead>
<tbody>
<tr>
<td>INU only</td>
<td>35m</td>
<td>25m</td>
<td>18m</td>
<td>12m</td>
<td>6m</td>
</tr>
<tr>
<td>INU/VMS</td>
<td>35m</td>
<td>25m</td>
<td>18m</td>
<td>12m</td>
<td>10m</td>
</tr>
<tr>
<td>INU/VMS/GPS PPS</td>
<td>&lt;10m CEP</td>
<td>&lt;10m CEP</td>
<td>&lt;10m CEP</td>
<td>&lt;10m CEP</td>
<td>&lt;10m CEP</td>
</tr>
<tr>
<td>INU/VMS/GPS SPS</td>
<td>&lt;60m CEP</td>
<td>&lt;60m CEP</td>
<td>&lt;60m CEP</td>
<td>&lt;60m CEP</td>
<td>&lt;60m CEP</td>
</tr>
</tbody>
</table>

HEADING/POINTING ACCURACY

| Specified Accuracy (RMS) at ±65° Latitude | <4.0 mils | <2.0 mils | <1.0 mils | <0.70 mils | <0.50 mils |
| sec(lat)                                  | <1.69 mils | <0.85 mils | <0.42 mils | <0.3 mils  | <0.21 mils |

PITCH AND ROLL ACCURACY

| (RMS)                                      | <1.00 mils | <1.00 mils | <0.50 mils | <0.35 mils | <0.25 mils |

MAX ALIGNMENT TIME

| Maximum Static Alignment Time             | <5.0 minutes | <5.0 minutes | <10.0 minutes | <15.0 minutes | <20.0 minutes |
| Maximum Dynamic Alignment Time            | <12.0 minutes | <12.0 minutes | <12.0 minutes | <16.0 minutes | <16.0 minutes |
| Typical Alignment Time (28° Latitude)    | <2.5 minutes | <3.0 minutes | <4.5 minutes | <5.5 minutes | - |

Values shown are per definitions in gTALIN system specifications.